

Formula Sheet

Kinematics & Forces

$$v_x = \frac{dx}{dt} \quad a_x = \frac{dv_x}{dt}$$

$$\bar{v}_x = \frac{\Delta x}{\Delta t} \quad \bar{a}_x = \frac{\Delta v_x}{\Delta t}$$

Constant acceleration

$$x(t) = x_0 + v_0 t + \frac{1}{2} a t^2$$

$$v(t) = v_0 + a t$$

$$v_f^2 = v_0^2 + 2a\Delta x$$

$$\bar{v} = \frac{(v_f + v_0)}{2}$$

$$x(t) = x_0 + v t - \frac{1}{2} a t^2$$

(compare the above eqn. carefully to the first constant acc. eqn. before using.)

Projectile motion

$$v_x(t) = v_{0x}$$

$$x(t) = x_0 + v_{0x} t$$

$$v_y(t) = v_{0y} - g t$$

$$y(t) = y_0 + v_{0y} t - \frac{1}{2} g t^2$$

$$\Sigma F = ma$$

Uniform circular motion

$$a_c = \frac{v^2}{r}$$

$$v = \frac{2\pi r}{T} \quad T = \frac{1}{f}$$

Friction

$$f_s \leq \mu_s F_n$$

$$f_k = \mu_k F_n$$

$$F_{\text{grav}} = mg$$

$$F_{\text{spring}} = -kx$$

Vector Operations

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n}$$

$$\mathbf{i} \times \mathbf{j} = \mathbf{k}$$

$$\mathbf{j} \times \mathbf{k} = \mathbf{i}$$

$$\mathbf{k} \times \mathbf{i} = \mathbf{j}$$

Energy & Momentum

$$K = \frac{1}{2} m v^2 = \frac{p^2}{2m}$$

$$W = \int F_{\parallel} dx (= \int \mathbf{F} \cdot d\mathbf{r})$$

$$W_{\text{net}} = \Delta E_{\text{SYSTEM}} = \Delta E_{\text{Mech}} + \Delta E_{\text{Th}}$$

$$\Delta E_{\text{Th}} = f_k \Delta s$$

$$P_{\text{instantaneous}} = \frac{dW}{dt} = \mathbf{F} \cdot \mathbf{v}$$

$$\Delta U = -W \text{ of conservative force}$$

$$F(x) = - \frac{dU(x)}{dx}$$

$$U_{\text{spring}}(x) = \frac{1}{2} k x^2$$

$$U_g(y) = mgy \text{ [near the earth's surface]}$$

$$\mathbf{p} = m\mathbf{v}$$

$$\mathbf{I} = \text{Impulse} = \int \mathbf{F} dt = \mathbf{p}_f - \mathbf{p}_i = F_{\text{avg}} \Delta t = \Delta \mathbf{p}$$

Collisions:

$$\mathbf{P}_{\text{tot},f} = \mathbf{P}_{\text{tot},i}$$

Elastic collisions:

$$K_{\text{tot},f} = K_{\text{tot},i}$$

Center of mass:

$$M_{\text{tot}} \mathbf{r}_{\text{cm}} = m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2 + \dots$$

$$M_{\text{tot}} \mathbf{v}_{\text{cm}} = m_1 \mathbf{v}_1 + m_2 \mathbf{v}_2 + \dots$$

$$M_{\text{tot}} \mathbf{a}_{\text{cm}} = m_1 \mathbf{a}_1 + m_2 \mathbf{a}_2 + \dots$$

$$\mathbf{P}_{\text{tot}} = \mathbf{p}_{\text{cm}}$$

$$= M_{\text{tot}} \mathbf{v}_{\text{cm}} = m_1 \mathbf{v}_1 + m_2 \mathbf{v}_2 + \dots$$

$$\Sigma \mathbf{F}_{\text{ext}} = \frac{d\mathbf{P}_{\text{tot}}}{dt}$$

Rotation

$$\Delta \theta = \Delta s / r$$

$$\omega = \frac{d\theta}{dt} \quad \alpha = \frac{d\omega}{dt}$$

$$v_{\text{tang}} = \omega r$$

$$a_{\text{tang}} = \alpha r$$

$$a_{\text{rad}} = \frac{v^2}{r} = \omega^2 r$$

Constant acceleration

$$\theta(t) = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\omega(t) = \omega_0 + \alpha t$$

$$\omega_f^2 = \omega_0^2 + 2 \alpha \Delta \theta$$

$$\bar{\omega} = \frac{(\omega_f + \omega_0)}{2}$$

$$I = \Sigma m_i r_i^2 (= \int r^2 dm)$$

$$I_{\text{cm}} = mR^2, \text{ ring}$$

$$I_{\text{cm}} = \frac{1}{2} mR^2, \text{ disk}$$

$$I_{\text{cm}} = \frac{2}{5} mR^2, \text{ solid sphere}$$

$$I_{\text{cm}} = mL^2/12 \text{ for rod}$$

$$I_{\text{end}} = mL^2/3 \text{ for rod}$$

$$I_d = I_{\text{cm}} + Md^2$$

(parallel axis theorem.)

$$\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$$

$$|\boldsymbol{\tau}| = rF \sin \theta = r_{\perp} F = r F_{\perp}$$

$$\Sigma \boldsymbol{\tau} = \mathbf{I} \boldsymbol{\alpha}$$

$$W = \int \boldsymbol{\tau} d\theta$$

$$K = \frac{1}{2} I \omega^2$$

Rolling without slipping:

$$v_{\text{cm}} = \omega R$$

$$a_{\text{cm}} = \alpha R$$

Angular momentum

$$\mathbf{L} = \mathbf{r} \times \mathbf{p}$$

$$|\mathbf{L}| = r p \sin \theta = r_{\perp} p = r p_{\perp}$$

$$L = I\omega$$

$$\Sigma \boldsymbol{\tau}_{\text{ext}} = \frac{d\mathbf{L}_{\text{tot}}}{dt}$$

Gravitation

$$|F_g| = \frac{GMm}{r^2}$$

The force on mass 1 due to mass 2. The unit vector points to mass 2.

$$\vec{F}_{12} = \frac{GMm}{r^2} \hat{r}$$

Principle of Superposition

$$\vec{F}_{1,net} = \sum_{i=2}^n \vec{F}_{1i}$$

Gravitational P.E.

$$U_g(r) = -\frac{GMm}{r}$$

Oscillations in simple harmonic motion.

$$x(t) = x_{max} \cos(\omega t + \phi)$$

so $d^2x/dt^2 = -\omega^2 x(t)$

$$\theta(t) = \theta_m \cos(\omega t + \phi)$$

so $d^2\theta/dt^2 = -\omega^2 \theta(t)$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$\omega = \sqrt{\frac{k}{m}} : \text{spring}$$

$$T = 2\pi \sqrt{\frac{I}{MgD}} : \text{physical pendulum}$$

Fluids

$$p_h = p_o + \rho gh$$

$$g = 9.8 \text{ m/s}^2$$

$$G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$$

$$R_{earth} = 6.38 \times 10^6 \text{ m}$$

$$M_{earth} = 5.97 \times 10^{24} \text{ kg}$$

Units related to Pressure

$$1 \text{ Pa} = 1 \text{ N/m}^2$$

$$1 \text{ atm} = 1.013 \times 10^5 \text{ Pa}$$

$$\rho_{water} = 1000 \text{ kg/m}^3$$

Law of Cosines: $C^2 = A^2 + B^2 - 2AB \cos \gamma$

Law of Sines:
$$\frac{\sin \alpha}{A} = \frac{\sin \beta}{B} = \frac{\sin \gamma}{C}$$

