

Some very informal Notes on Linear Transformations [see any Linear Algebra textbook]

Remark: Linear transformations are functions from \mathbb{R}^n to \mathbb{R}^m which preserves the vector structure of \mathbb{R}^n and \mathbb{R}^m .

That is a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ satisfies

- i) $T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w})$ for all vectors \vec{v} and \vec{w} in \mathbb{R}^n
 and ii) $T(c\vec{v}) = cT(\vec{v})$ for all vectors $\vec{v} \in \mathbb{R}^n$ and scalars $c \in \mathbb{R}$.

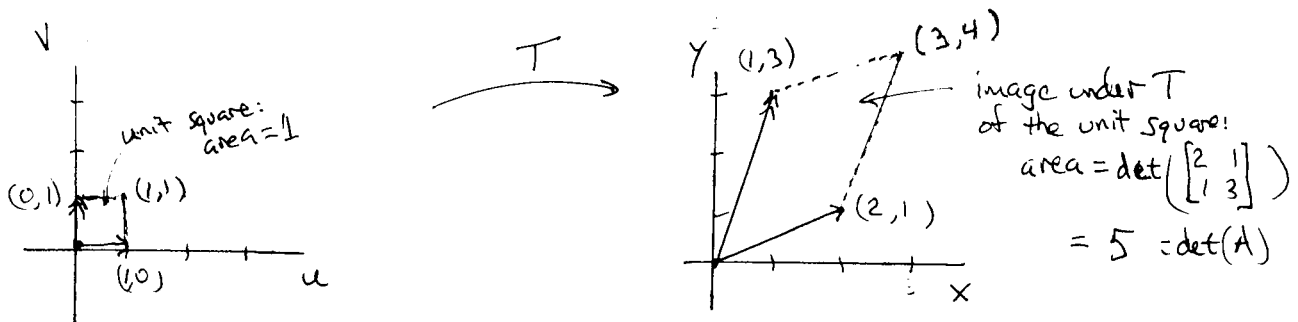
One can show that a given linear transformation T can be represented by multiplication on the left by a certain $m \times n$ matrix.

example: If $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ has the property that

$$T(1,0) = (2,1) \text{ and } T(0,1) = (1,3)$$

then $T(u,v) = (x,y)$ where the relation between (u,v) in the domain of T and (x,y) in the range of T is given by

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = A \begin{bmatrix} u \\ v \end{bmatrix} \text{ where } A = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix}$$



Facts about linear transformations:

- ① Under T , the image of a line through the origin is a line through the origin.
- ② Parallel lines map to parallel lines, so parallelograms map to parallelograms. Also parallel planes map to parallel planes, etc..

Facts about linear transformations [cont'd]

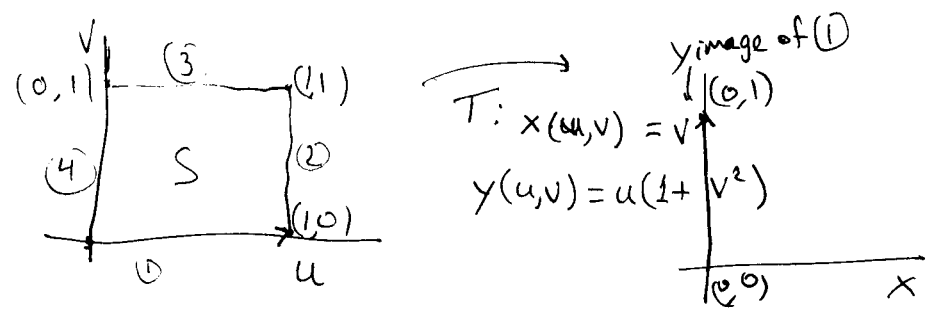
- (3) If $n=m$, $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is represented by an $n \times n$ matrix A and $\det(A) = \pm$ area (or volume or hypervolume) of the image of the unit square (or cube or hypercube),
- '+' if T preserves orientation (maps counterclockwise-oriented parallelograms to counter-clockwise oriented parallelograms),
 - '-' if T reverses orientation.
- If $\det(A) = 0$, the image of the unit square is a degenerate parallelogram having zero area, which means that T is not one-to-one.

- (4) If $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is one-to-one (i.e. $\det(A) \neq 0$) then T^{-1} is also a linear transformation and is represented by the $n \times n$ matrix A^{-1} .

- (5) If $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is represented by the $m \times n$ matrix A and $S: \mathbb{R}^m \rightarrow \mathbb{R}^p$ is represented by the $p \times m$ matrix B then $S \circ T: \mathbb{R}^n \rightarrow \mathbb{R}^p$ is ^{a linear transformation} represented by the $p \times n$ matrix BA .
- and $\det(BA) = \det(B) \cdot \det(A)$.

15.10 Double (and Triple) integrals under a change of variables

8) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ will be a non-linear transformation



For example $T(0,0) = (0,0)$
 $T(1,0) = (0, 1 \cdot (1+0^2)) = (0,1)$

$S = \{(u,v) \mid S \text{ is bounded by } u=0, u=1, v=0, v=1\}$.

Image of line (1) under T ? On (1): $u = \text{variable}, v=0$

So $x [= v] = 0$ and $y [= u(1+v^2)] = u$

parametric curve: $x(u) = 0$ $0 \leq u \leq 1$
 $y(u) = u$

Image of (2)? On (2) $u=1, 0 \leq v \leq 1$

$x(1,v) = v$
 $y(1,v) = 1 \cdot (1+v^2) = 1+v^2$

we can eliminate the parameter:
 $y = 1+x^2$

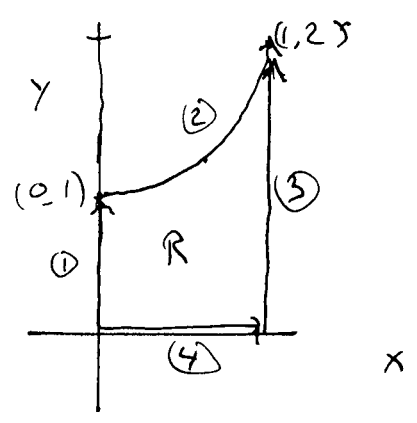
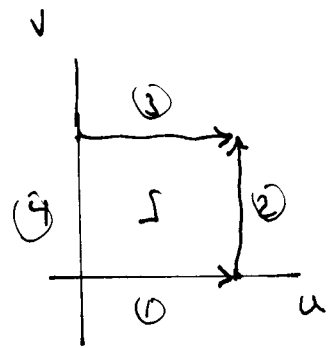


Image of (3)? On (3): $v=1, 0 \leq u \leq 1$

$$x(u, v) = x(u, 1) = 1$$

$$y(u, v) = y(u, 1) = u(1+1^2) = 2u$$

Image of (4)? On (4): $u=0, 0 \leq v \leq 1$

$$x(0, v) = v$$

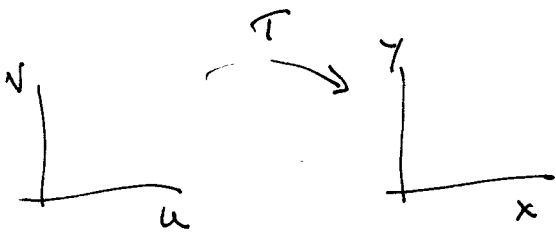
$$y(0, v) = 0(1+v^2) = 0$$

Defn:

The Jacobian of a transformation T

given by $\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$

is denoted $\frac{\partial(x, y)}{\partial(u, v)}$



and is calculated as:

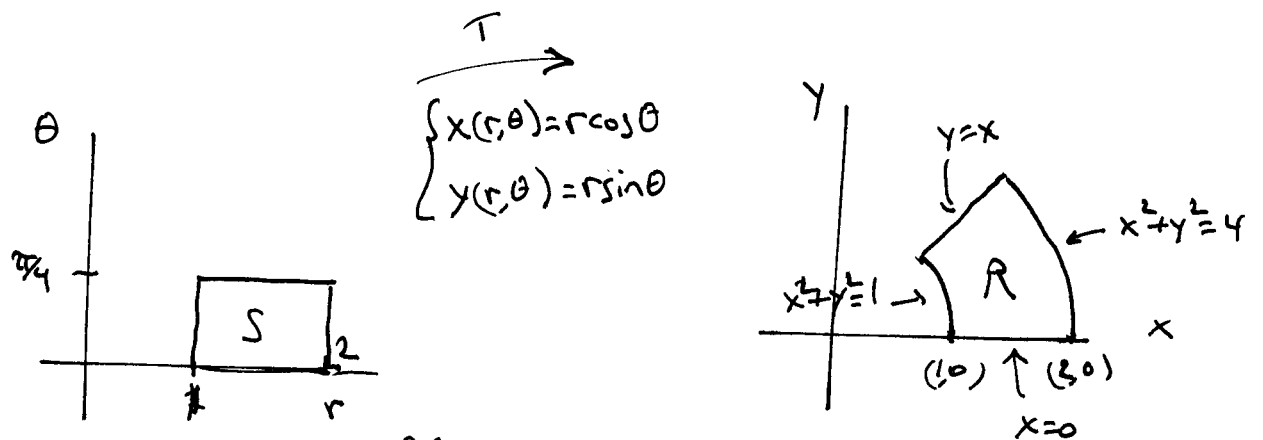
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

ex: The Jacobian for T in problem 8 where $\begin{cases} x = v \\ y = u(1+v^2) \end{cases}$

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 1 \\ 1+v^2 & 2uv \end{vmatrix} = -(1+v^2) = \text{distortion of area under } T$$

Polar coordinates as a change of variables



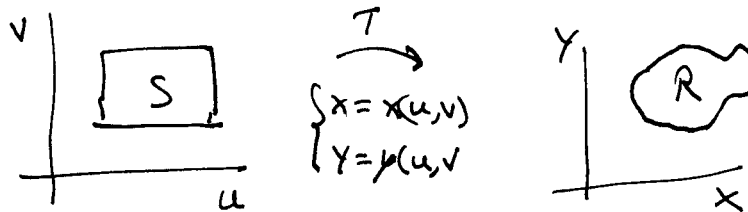
$$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$

$$= (\cos \theta)(r \cos \theta) - (\sin \theta)(-r \sin \theta)$$

$$= r \cos^2 \theta + r \sin^2 \theta$$

$$= r (\cos^2 \theta + \sin^2 \theta) = \boxed{r}$$

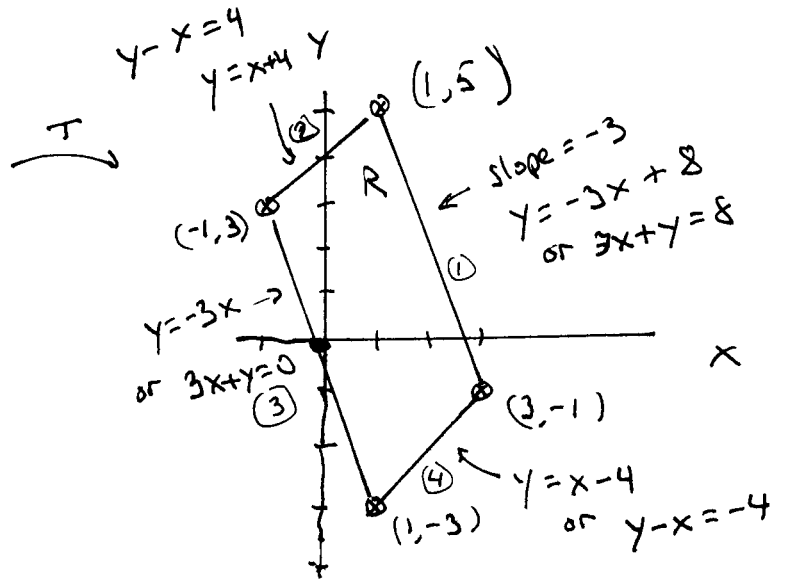
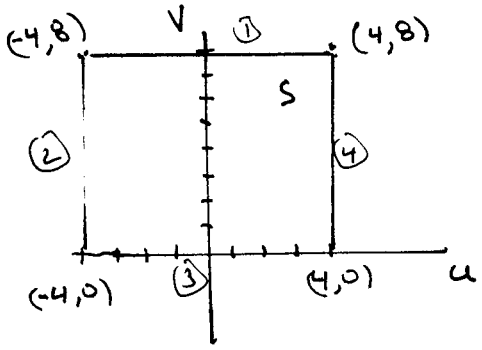
Theorem 9:
p 1068



$$\iint_R f(x,y) dx dy = \iint_S f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

16) $\iint_R (4x+8y) dA$

R is a parallelogram with vertices $(-1,3), (1,-3), (3,-1), (1,5)$



T: $x = \frac{1}{4}(u+v)$
 $y = \frac{1}{4}(v-3u)$

$\therefore \frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{1}{4} & \frac{1}{4} \\ -\frac{3}{4} & \frac{1}{4} \end{vmatrix} = \frac{1}{4}$

Boundaries of S? $\textcircled{1}$ $3x+y=8$ becomes $3 \cdot \frac{1}{4}(u+v) + \frac{1}{4}(v-3u) = 8$

or $\frac{3}{4}u + \frac{3}{4}v + \frac{1}{4}v - \frac{3}{4}u = 8$

or $v=8$

$\textcircled{3}$ $3x+y=0$ becomes $3 \cdot \frac{1}{4}(u+v) + \frac{1}{4}(v-3u) = 0$

or $v=0$

$\textcircled{2}$ $y-x=4$ becomes $\frac{1}{4}(v-3u) - \frac{1}{4}(u+v) = 4$

or $\frac{1}{4}v - \frac{3}{4}u - \frac{1}{4}u - \frac{1}{4}v = 4$

or $-u=4$ or $u=-4$

$\textcircled{4}$ $y-x=-4$ becomes $\frac{1}{4}(v-3u) - \frac{1}{4}(u+v) = -4$

or $u=4$

[Finished after end of class]

(6 cont'd) The integrand $f(x, y)$ of the integral we want to calculate becomes, under the change of variables:

$$\begin{aligned} 4x + 8y &= 4 \cdot \frac{1}{4}(u+v) + 8 \cdot \frac{1}{4}(v-3u) \\ &= u+v + 2v - 6u \\ &= -5u + 3v \end{aligned}$$

We're now ready to calculate the integral:

$$\begin{aligned} \iint_R (4x + 8y) \, dx \, dy &= \iint_S (-5u + 3v) \frac{\partial(x, y)}{\partial(u, v)} \, du \, dv \\ &= \int_0^8 \int_{-4}^4 (-5u + 3v) \cdot \frac{1}{4} \, du \, dv \\ &= -\frac{5}{4} \int_0^8 \int_{-4}^4 u \, du \, dv + \frac{3}{4} \int_0^8 \int_{-4}^4 v \, du \, dv \\ &= -\frac{5}{4} \cdot \int_{-4}^4 u \, du \cdot \int_0^8 dv + \frac{3}{4} \cdot \int_{-4}^4 du \cdot \int_0^8 v \, dv \\ &= \frac{3}{4} \left[u \right]_{-4}^4 \left[\frac{v^2}{2} \right]_0^8 \\ &= \frac{3}{4} [4 - (-4)] [32 - 0] \\ &= \frac{3}{4} \cdot 8 \cdot 32 = \boxed{192} \end{aligned}$$

Remark: In this example, the transformation T is a linear transformation represented by

$$\begin{bmatrix} x \\ y \end{bmatrix} = A \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} \\ -\frac{3}{4} & \frac{1}{4} \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} \quad \text{and} \quad \det(A) = \frac{\partial(x, y)}{\partial(u, v)} = \frac{1}{4} \quad \text{shows } T \text{ diminishes area by a factor of } \frac{1}{4}.$$