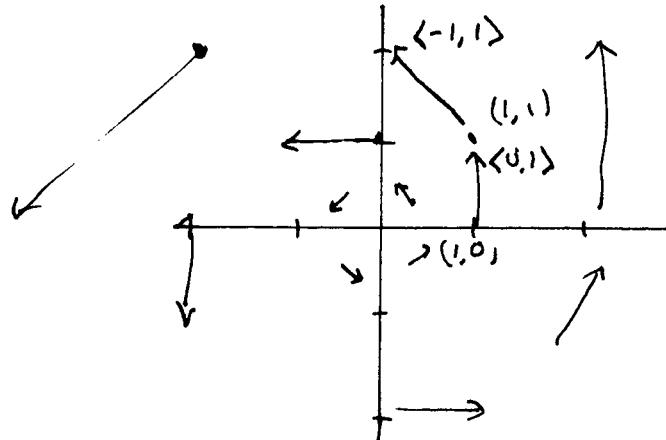


16.1 Vector fields

Example: $\vec{F}(x, y) = \langle -y, x \rangle$

(x, y)	$\langle -y, x \rangle$
$(1, 0)$	$\langle 0, 1 \rangle$
$(0, 1)$	$\langle -1, 0 \rangle$
$(1, 1)$	$\langle -1, 1 \rangle$
$(1, 2)$	$\langle -2, 1 \rangle$
$(0, 0)$	$\langle 0, 0 \rangle$



Remark. Every gradient vector field is a vector field.

ex. $f(x, y) = x^2 y$

$$\begin{aligned} \vec{F}(x, y) &= \nabla f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle = \langle 2xy, x^2 \rangle \\ &= \langle P(x, y), Q(x, y) \rangle \end{aligned}$$

where $P(x, y) = 2xy$,
and $Q(x, y) = x^2$.

Observe: In this case that $\vec{F}(x, y) = \nabla f(x, y) = \text{a gradient}$
we have that $\frac{\partial P}{\partial y} = f_{xy}(x, y) = 2x = f_{yx}(x, y) = \frac{\partial Q}{\partial x}$.
equal by Clairaut's theorem

That is,
$$\boxed{\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}}$$
 ← Test for conservative
vector fields

So, is every vector field the gradient $\nabla f(x,y)$ for some real-valued function $f(x,y)$?

Nope. In the first example $\vec{F}(x,y) = \langle P(x,y), Q(x,y) \rangle = \langle -y, x \rangle$

$$\frac{\partial P}{\partial y} = \frac{\partial}{\partial y}[-y] = -1 \neq 1 = \frac{\partial Q}{\partial x}[x] = \frac{\partial Q}{\partial x}.$$

Defn: A vector field $\vec{F}(x,y)$ is a conservative vector field if $\vec{F}(x,y) = \nabla f(x,y)$ for some real-valued function (or "scalar field") $f(x,y)$. If so, $f(x,y)$ is called a potential function for \vec{F} .

Ex: Is the following vector field conservative?

$$\begin{aligned} F(x,y) &= \langle 3x^2 - 2y^2, 4xy + 3 \rangle && [\text{§16.3}] \\ &= \langle P(x,y), Q(x,y) \rangle && [\#6] \end{aligned}$$

$$\begin{aligned} \frac{\partial Q}{\partial x} &= \frac{\partial}{\partial x}[4xy + 3] = 4y && \leftarrow \text{Not equal, so} \\ \frac{\partial P}{\partial y} &= \frac{\partial}{\partial y}[3x^2 - 2y^2] = -4y && \text{not conservative;} \\ &&& \text{that is, } F \neq \nabla f(x,y) \end{aligned}$$

Equivalent form
of the conservative
test:

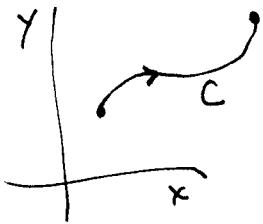
$$\begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ P & Q \end{vmatrix} = \frac{\partial}{\partial x} - \frac{\partial P}{\partial y} = 0 ?$$

16.2 Line integrals

Remark: There are two types of line integrals

- Line integral of a real-valued function

$$\int_C f(x, y) ds.$$



Intuitively, this is "weighted arc length"

where $ds = \text{element of arc length (in cm)}$

and $f(x, y) = \text{mass density (g/cm)} \text{ of a wire.}$

Then $\int_C f(g/cm) \cdot ds(cm) = \text{mass (g)}$

- Line integral of a vector field $\vec{F} = \langle P(x, y), Q(x, y) \rangle$

$$\int_C P(x, y) dx + Q(x, y) dy = \int \vec{F} \cdot d\vec{r}$$

In physics, this is how we calculate work.

Defn: For a parametric curve $\begin{cases} x = x(t) \\ y = y(t) \end{cases}$ [Equivalent:
 $\vec{r}(t) = \langle x(t), y(t) \rangle$]
 $a \leq t \leq b$

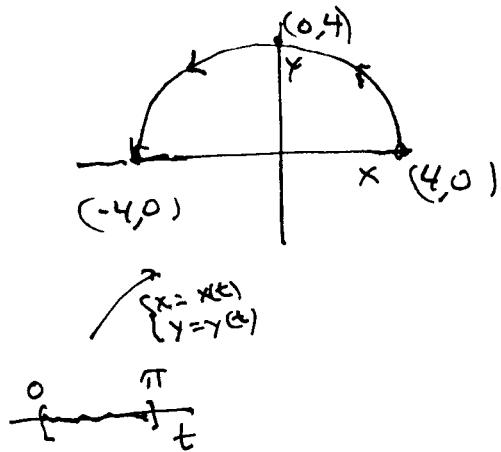
and a real-valued function $f(x, y)$

$$\begin{aligned} \int_C f(x, y) ds &= \int_{t=a}^b f(x(t), y(t)) \frac{ds}{dt} dt \\ &= \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \end{aligned}$$

(4)

Evaluate

$$\text{ex: } \int_C y \, ds \quad \text{where} \quad C: \begin{cases} x = 4 \cos t \\ y = 4 \sin t \\ 0 \leq t \leq \pi \end{cases}$$



$$\frac{dx}{dt} = -4 \sin t$$

$$\frac{dy}{dt} = 4 \cos t$$

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} = \sqrt{16 \sin^2 t + 16 \cos^2 t} = 4$$

$$\int_C y \, ds = \int_0^\pi \underbrace{(4 \sin t)}_y \cdot \underbrace{4}_{\frac{ds}{dt}} \, dt = 16 \int_0^\pi \sin t \, dt$$

$$= -16 \cos t \Big|_0^\pi$$

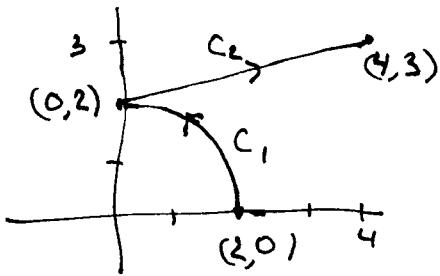
$$= -16[\cos \pi - \cos 0]$$

$$= -16[-1 - 1] = \boxed{32}$$

ex: Evaluate $\int_C x \, ds$ for the same C . Answer: 0
[Note: Symmetry].

8) Evaluate $\int_C x^2 dx + y^2 dy$

where C consists of the arc of the circle $x^2 + y^2 = 4$ from $(2,0)$ to $(0,2)$ followed by the line segment from $(0,2)$ to $(4,3)$.



For C_1 , take $\begin{cases} x = 2 \cos t \\ y = 2 \sin t \\ 0 \leq t \leq \pi/2 \end{cases}$ to be the parametrization,

$$\begin{aligned} dx &= -2 \sin t dt \\ dy &= 2 \cos t dt \end{aligned}$$

$$\begin{aligned} \int_{C_1} x^2 dx + y^2 dy &= \int_0^{\pi/2} [(2 \cos t)^2 (-2 \sin t) + (2 \sin t)^2 (2 \cos t)] dt \\ &= -8 \int_0^{\pi/2} \cos^2 t \sin t dt + 8 \int_0^{\pi/2} \sin^2 t \cos t dt \\ &= 8 \int_0^{\pi/2} \cos^2 t d(\cos t) + 8 \int_0^{\pi/2} \sin^2 t d(\sin t) \\ &= \left[\frac{8}{3} \cos^3 t + \frac{8}{3} \sin^3 t \right]_0^{\pi/2} \\ &= \frac{8}{3} - \frac{8}{3} = 0 \quad (\text{to be continued}) \end{aligned}$$

[Added after the end of class...]

8 cont'd)

For C_2 , we can parametrize the line from $(0, 2)$ to $(4, 3)$ by letting x itself be the parameter.

$$\begin{cases} x = t \\ y = \frac{1}{4}t + 2 \end{cases} \quad \begin{array}{l} \text{so that when } t=0, (x,y) = (0,2) \\ \text{and when } t=4, (x,y) = (4,3). \end{array}$$

$0 \leq t \leq 4$

Then $\begin{cases} dx = dt \\ dy = \frac{1}{4}dt \end{cases}$ and

$$\begin{aligned} \int_{C_2} x^2 dx + y^2 dy &= \int_0^4 \left([x(t)]^2 \frac{dx}{dt} + [y(t)]^2 \frac{dy}{dt} \right) dt \\ &= \int_0^4 \left[(t^2)(1) + \left(\frac{t}{4} + 2\right)^2 \frac{1}{4} \right] dt = \int_0^4 \left(t^2 + \frac{1}{16}t^2 + \frac{1}{4}t + 1 \right) dt \\ &= \int_0^4 \left(\frac{65}{64}t^2 + \frac{1}{4}t + 1 \right) dt = \left[\frac{65}{192}t^3 + \frac{1}{8}t^2 + t \right]_0^4 \\ &= \frac{65}{3} + 2 + 4 = \frac{83}{3} = 27.\bar{6} \end{aligned}$$

$$\therefore \int_C x^2 dx + y^2 dy = \int_{C_1} x^2 dx + y^2 dy + \int_{C_2} x^2 dx + y^2 dy = 0 + \frac{83}{3} = \boxed{\frac{83}{3}}$$

- Remarks : (1) The result of the calculation of a line integral of a real-valued function $\int_C f(x,y) ds$, does not depend on the particular parametrization of C .
- (2) The line integral of a vector field, $\int_C P dx + Q dy$, does not depend on the parametrization of the curve C , except that reversing the orientation of C has the effect of toggling the sign of $\int_C P dx + Q dy$. That is, if $-C$ denotes the curve C with reversed orientation, $\int_{-C} P dx + Q dy = - \int_C P dx + Q dy$.